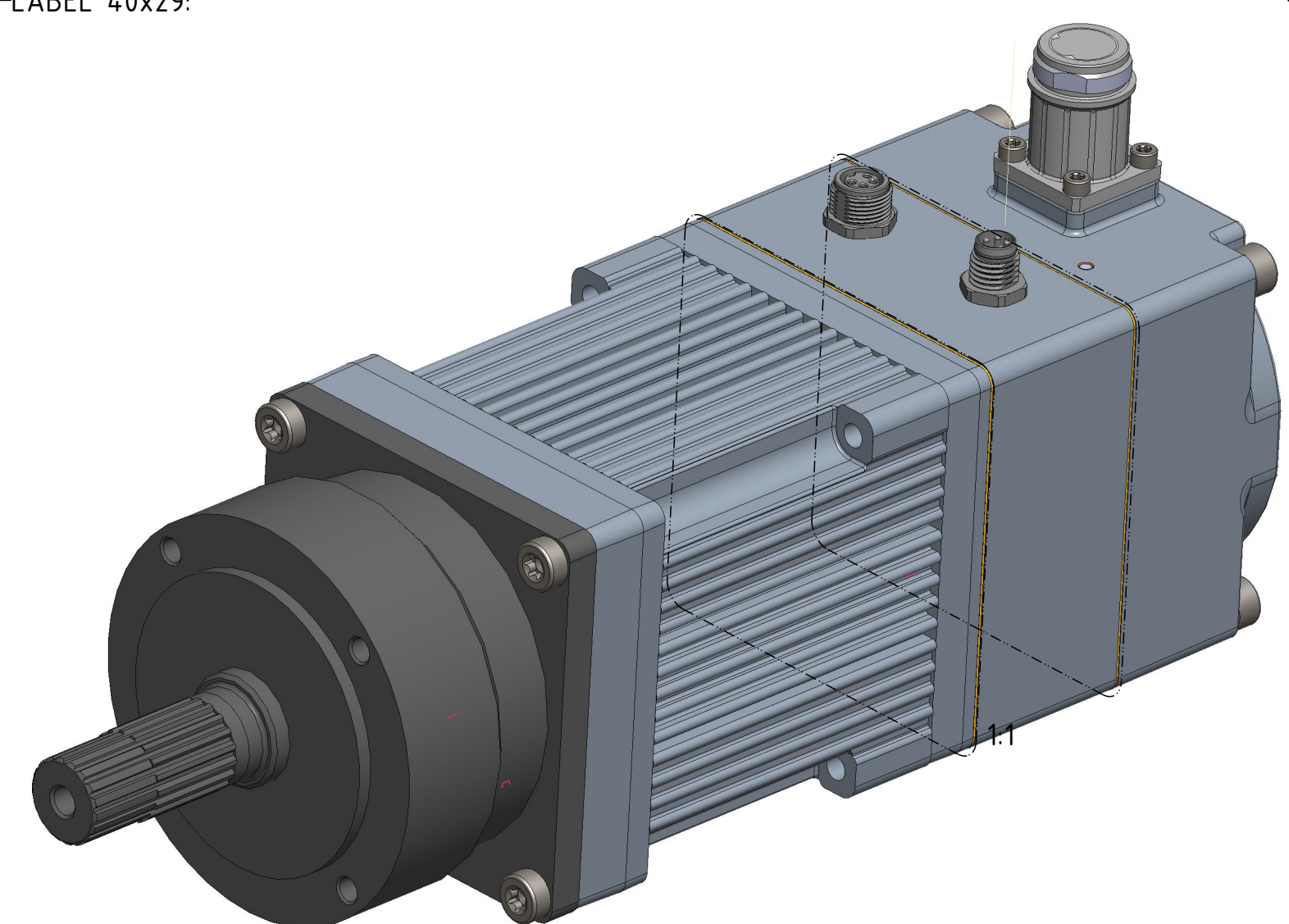
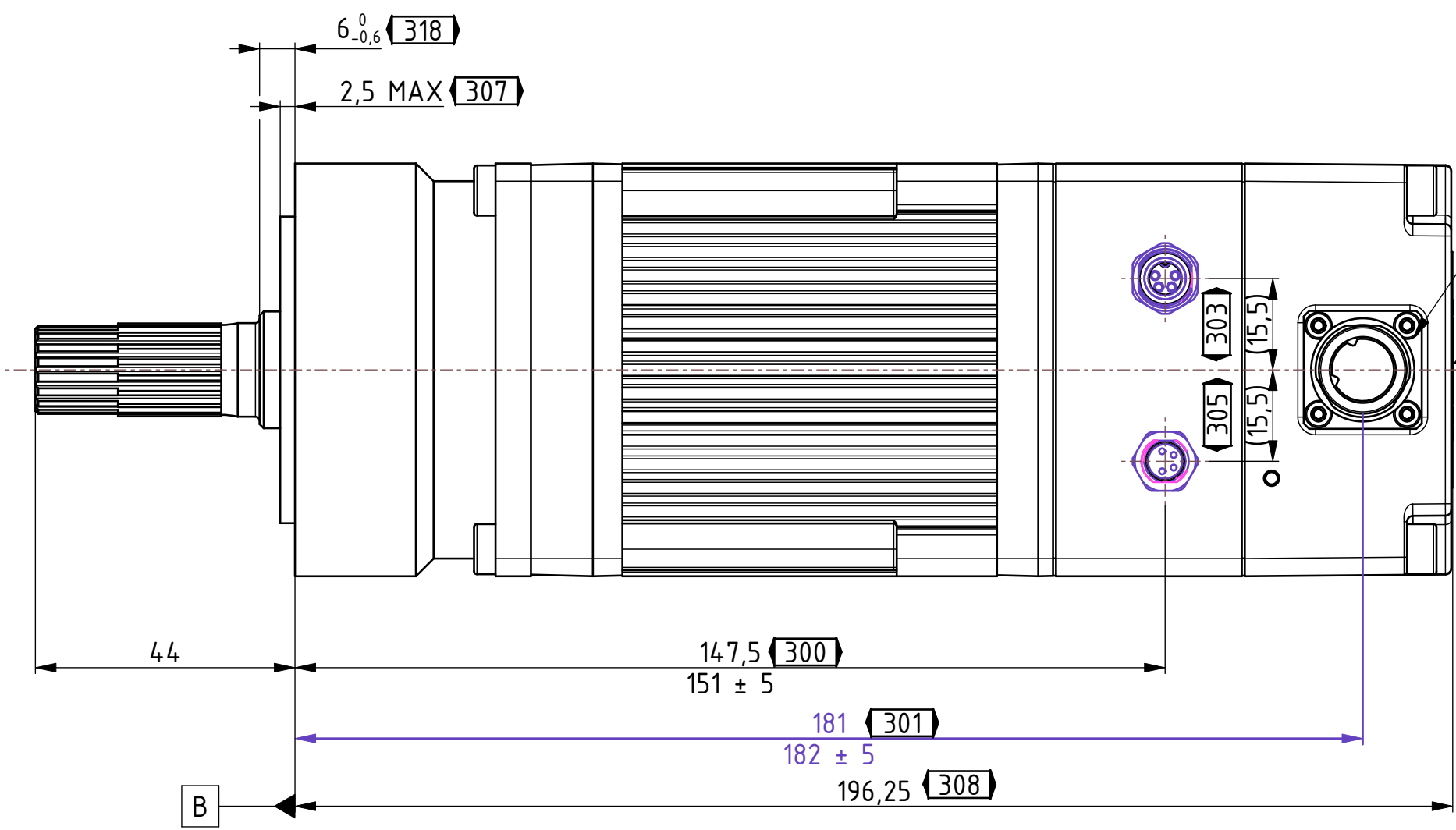
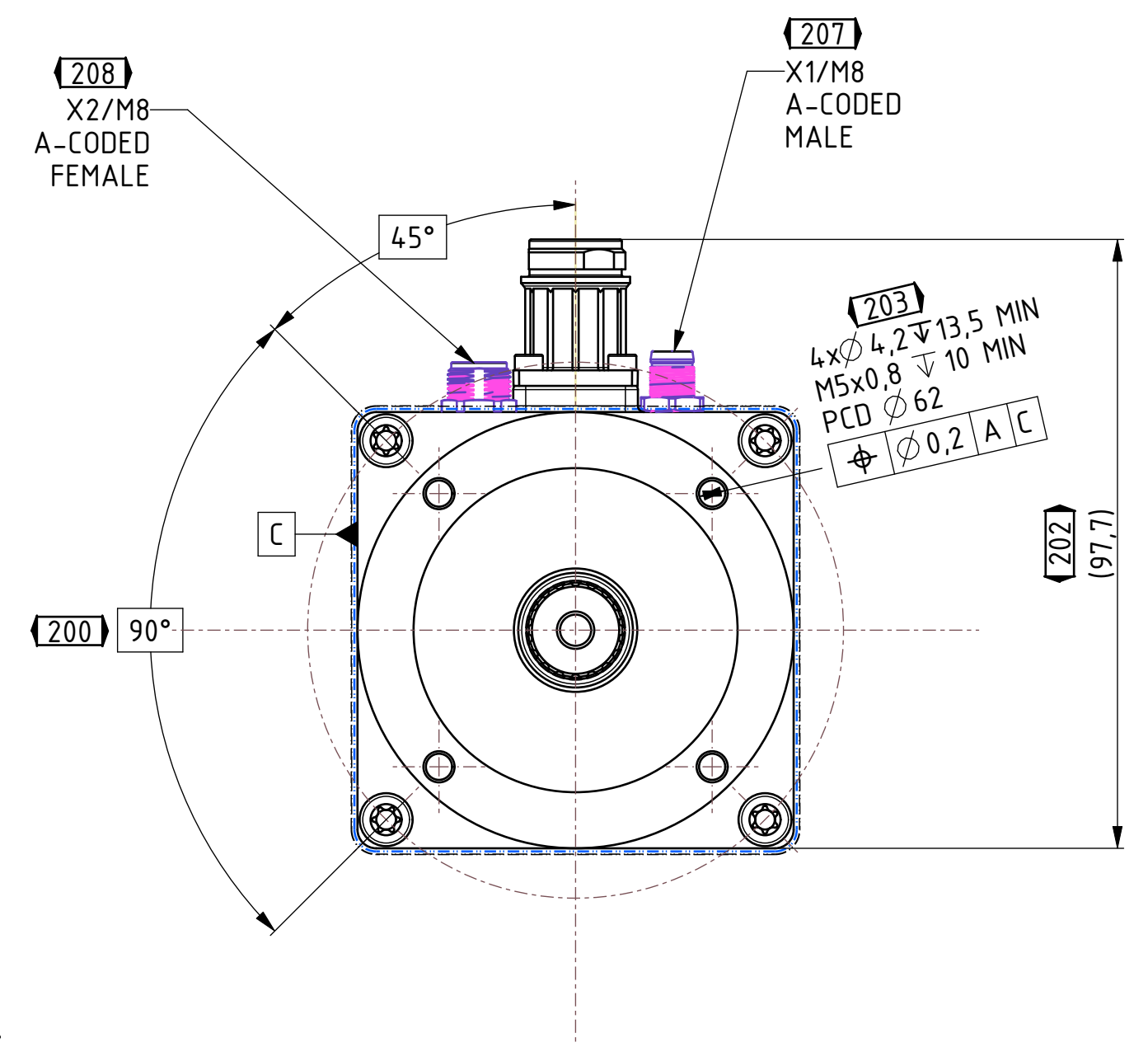
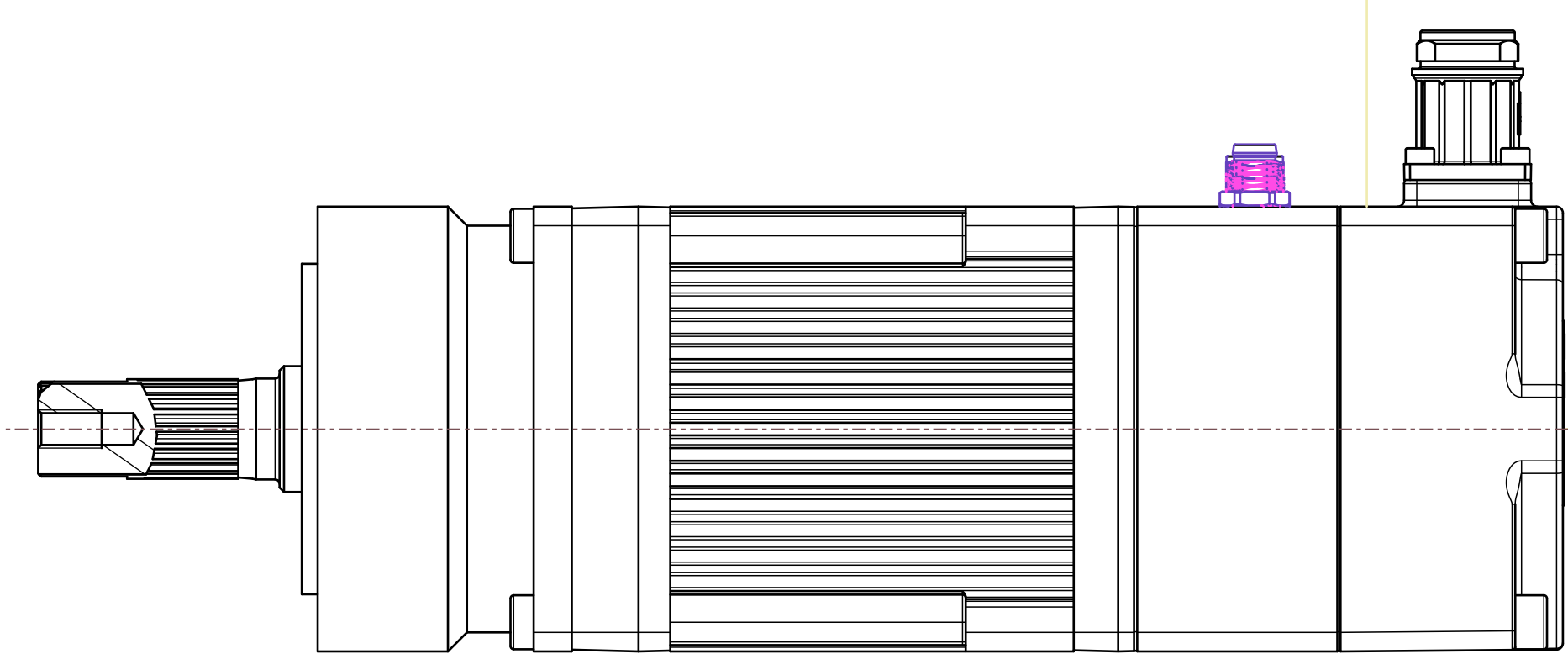


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500
Power connector pinout:

Pin number	Signal	Description
A	48V power supply	[48:60]V power supply voltage <25A
B	GND power supply	Ground for power supply <25A
C	NC	NC
PE	PE	PE
1	Logic supply	[10:26]V logic supply voltage <0.5A
2	NC	NC
+	Brake supply	[22:26]V brake supply voltage Continuous<0.5A
-	24V Brake maintain/status	[0:26]V holding brake status Continuous<0.5A

502
CAN connector pinout:

Pin Number	Signal
1	CAN-IN H
2	CAN-IN L
3	GND
4	NC

Notes : **501**
1. according to motor specification 009854 SRS Climbing geared motor with embedded driver
2. No axial/radial force should be applied onto output shaft until motor is fully assembled on robot

Kupec/Customer Part No.	Rev	Status	Format		SAP ID	Koda/Code	Masa/Mass[kg]
Standard	B	In Work	A2		1152395	13_2409_05	3,00
	ECN	2409-26500	Merilo Scale	1:2	Naziv/Title		
	Datum Date	06.11.2025	List Sheet	1/1			
	Izdelal Created	Martin Trček			BL62 I 45		
Hrapavost površine/Surface	KOLEKTOR			2D	BL62_45_13_2409_05_1152395/.0		
				3D	065_2409_05_ASSEMBLY_CLIMBING/B.7		